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Nonlinear Observer Design for PEM Fuel-Cell Systems using First-Order Sliding Mode Techniques Zakaria BAROUD, Atallah BENALIA Electrical Engineering Department, LACoSERE Laboratory Amar Telidji University, Laghouat, Algeria E-mail: [zbaroud, abenalia]@lagh-univdz Carlos OCAMPO-MARTINEZ Universitat Polit`ecnica de Catalunya Institut de Robotica`

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Design of a robust Controller/Observer for TCP/AQM network ...

robust nonlinear observers or control laws Unfortunately, building upon this peculiar observer provides for bounded input-bounded state (BIBS) In order to tackle a wide range of applications, various implementations of TCP models in terms of assumptions and numerical techniques [18], [19], [20] exist

First supervisor: Second supervisor

[7] D Boutat and K Busawon, On the transformation of nonlinear dynamical systems into the Extended Nonlinear Observable Canonical Form TCON, International Journal of Control, 2010 [8] D Boutat, Extended nonlinear observer normal forms for a class of nonlinear dynamical

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